Bounded Pairs in 1-D and 2-D Models

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How does our system evolve as a result of its initial state?



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Dynamics of a system with initial state |110000>



Bounded pair away from the defect



The system can evolve into 2 configurations



Quantum Interference

Given the initial state |011000> with the defect still being on site 5, we would expect that this state could have two options to move forward:



The system can evolve into 2 configurations

Initial state: 001100

 $J_z = 10$, Eps = 10 Energy of system = $J_z/2 - Eps/2 = 0$



If the defect is on the 5th site: 001100/001010



Initial 001010 has the same energy as 001100 and in dynamics that state appears. The sum of theses two graphs equals 1, implying 100% participation.





Dynamics of a system with initial state |101000>



Unbounded up-spins away from the defect

→ ↑ → ↓ → ↓ Defect

The initial state has an energy of $-J_z/2 - eps/2 = -10$. This number is from the J_z value: $J_z = 10$. If we count the Ising interactions, we get the value of $-J_z/2$. The defect does not contribute to the energy of the system as the up-spins are far from it.

Dynamics of a system with initial state |000110>



Bounded pair on defect



The initial state has an energy of

 $J_{z}/2 + Eps/2 = 5 + 5 = 10.$



Bound pairs in 1-D are robust

What did we understand up to this point?

Bound pairs cannot split even if we have a defect that would allow for it in energy conservation.



Will this persist in a 2-D system where there are many more possible channels for our excitations to move?



Site Interactions in 2-D

• The matrices on the right represent a 3x3 2-D system.

| | 1 | 1 | 0 | 1 | 1 | Θ | 1) |
|---|---|---|---|---|-----|---|----|
| | Θ | Θ | Θ | , | Θ | Θ | Θ |
| Į | 0 | Θ | 0 | | (O | Θ | 0) |
| 8 | 0 | 1 | 1 | Ĩ | 0 | 1 | 0 |
| | Θ | Θ | Θ | , | 1 | Θ | 0 |
| į | 0 | Θ | Θ | | 0 | Θ | 0) |



Our 2-D System



- Similarly to our 1-D system, the first and last site connect, forming a chain. With a 2-D system, the first and last site of every column connect as well. Ultimately, this forms a donut like shape, as displayed in the image to the left.
- It's important to note that the the inner circle does not correspond to a stronger interaction.



Every Basis in the 2-D System

| $\left\{ egin{pmatrix} 1 \\ 0 \\ 0 \end{bmatrix} ight\}$ | 1 0 0 | $\left[\begin{smallmatrix} 0 \\ 0 \\ 0 \end{smallmatrix} \right]$, | $\left(\begin{array}{c} 1\\ 0\\ 0\end{array}\right)$ | 0 0 0 | 1 0 0), | (1 1 0 | 0 0 0 | $\begin{bmatrix} \mathbf{O} \\ \mathbf{O} \\ \mathbf{O} \end{bmatrix}, \begin{bmatrix} \mathbf{O} \\ \mathbf{O} \end{bmatrix}$ | 1 (9] 9 (| 9 1 9 | 0 0 0), | $\left(\begin{array}{c}1\\0\\0\end{array}\right)$ | 0 0 0 | 0 1 0 | , | (1 0 1 | 0 0 0 | $\left[\begin{smallmatrix} 0 \\ 0 \\ 0 \end{smallmatrix} \right]$, | $\left(\begin{array}{c}1\\0\\0\end{array}\right)$ | 0 0 1 | 0 0), | $\left(\begin{array}{c}1\\0\\0\end{array}\right)$ | 0 0 0 | $\left. \begin{smallmatrix} 0 \\ 0 \\ 1 \end{smallmatrix} \right)$, | $\left(\begin{array}{c} 0\\ 0\\ 0\\ 0 \end{array}\right)$ | 1 0 0 | 1 0 0 | , |
|---|-------------|---|---|-------------|---|---|-------------|--|-------------------|-------------|---|---|-------------|-------------|---|--|-------------|--|---|-------------|--|---|-------------|--|--|-------------|-------------|---|
| (0 1 0 | 1 0 0 | $\left. \begin{smallmatrix} \mathbf{O} \\ \mathbf{O} \\ \mathbf{O} \\ \mathbf{O} \end{smallmatrix} \right)$, | $\left(\begin{array}{c} 0\\ 0\\ 0\\ 0 \end{array}\right)$ | 1 1 0 | 0 0 0), | $\left(\begin{array}{c} \mathbf{O}\\ \mathbf{O}\\ \mathbf{O}\\ \mathbf{O}\end{array}\right)$ | 1 0 0 | $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ | 9 1 9 (1 (| 1 9 9 | ⊙ ⊙ ⊙), | $\left(\begin{array}{c} 0\\ 0\\ 0\\ 0 \end{array}\right)$ | 1 0 1 | 0 0 0 | , | $\left(\begin{array}{c} \Theta\\ \Theta\\ \Theta\\ \Theta\end{array}\right)$ | 1 0 0 | 0 0 1 | (0 1 0 | 0 0 0 | $\begin{bmatrix} 1\\0\\0 \end{bmatrix}$, | $\left(\begin{array}{c} 0\\ 0\\ 0\\ 0 \end{array}\right)$ | 0 1 0 | $\begin{bmatrix} 1\\0\\0 \end{bmatrix}$, | $\left(\begin{array}{c} 0\\ 0\\ 0\\ 0 \end{array}\right)$ | 0 0 0 | 1 1 0 | , |
| (0 0 1 | 0 0 0 | $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, | $\left(\begin{array}{c} 0\\ 0\\ 0\\ 0 \end{array}\right)$ | 0 0 1 | $\left. \begin{smallmatrix} \mathbf{l} \\ 0 \\ 0 \end{smallmatrix} \right)$, | $\left(\begin{array}{c} \mathbf{O}\\ \mathbf{O}\\ \mathbf{O}\\ \mathbf{O} \end{array}\right)$ | 0 0 0 | 1 0 1), (| 9 (1 1 9 (| 9 1 9 | ⊙ ⊙ ⊙), | $\left(\begin{array}{c} 0 \\ 1 \\ 0 \end{array} \right)$ | 0 0 0 | 0 1 0 | , | (0 1 1 | 0 0 0 | ⊙ ⊙ ⊙), | $\left(\begin{array}{c} 0 \\ 1 \\ 0 \end{array} \right)$ | 0 0 1 | ⊙ ⊙ ⊙), | $\left(\begin{array}{c} 0\\ 1\\ 0 \end{array}\right)$ | 0 0 0 | 0 0 1 | $\left(\begin{array}{c} 0\\ 0\\ 0\\ 0 \end{array}\right)$ | 0 1 0 | 0 1 0 | , |
| (0 0 1 | 0 1 0 | $\left. \begin{array}{c} 0 \\ 0 \\ 0 \end{array} \right)$, | $\left(\begin{array}{c} 0\\ 0\\ 0 \end{array}\right)$ | 0 1 1 | 0 0 0), | $\left(\begin{array}{c} 0\\ 0\\ 0\\ 0 \end{array}\right)$ | 0 1 0 | $\begin{bmatrix} 0\\0\\1 \end{bmatrix}$, (| 9 (9 (1 (| 0 0 0 | $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$, | $\left(\begin{array}{c} 0\\ 0\\ 0\\ 0 \end{array}\right)$ | 0 0 1 | 0 1 0 | , | $\left(\begin{array}{c} 0\\ 0\\ 0\\ 0 \end{array}\right)$ | 0 0 0 | 0 1 1 | (0 0 1 | 0 0 1 | $\left. \begin{smallmatrix} 0 \\ 0 \\ 0 \end{smallmatrix} \right)$, | (0 0 1 | 0 0 0 | 0 0 1 | $\left(\begin{array}{c} \Theta\\ \Theta\\ \Theta\\ \Theta\end{array}\right)$ | 0 0 1 | 0 0 1 | } |

Stability in the Presence of a Defect?

Defect is on site 1



Different Initial States within the 2-D System

- BP are stable, this becomes more clear as we increase the system size
- And it is really just like a 1-D system in terms of the patterns of its dynamics, even with the defect
- When we introduce a defect to the system, the 2-D system evolves much like the 1-D system



Conclusion

- Working with my dear colleague and friend Eliana
- Benefits of taking the time to study doublons in both 1-D and 2-D models
- Working with the legendary Dr. Lea Santos

